

MORFOSE

Datasheet

COBOT

General information

Number of axes	4 axes		5 axes		6 axes	
Arm size	S	M	S	M	S	M
Max payload	27 kg	16 kg	15 kg	8 kg	11 kg	5 kg
Range	740 mm	1040 mm	820 mm	1120 mm	900 mm	1200 mm
Programming	graphical user interface 10" touchscreen + 20 physical buttons					
Mounting	every direction					
Footprint	diam. < 200 mm					
Materials	Aluminium, steel					
Cable length (robot arm)	5 m (can be changed on demand)					
Weight including cable	< 40 kg					

Modular assembly

Reconfiguration time	10 minutes
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Performance

Repeatability (ISO 9283)	+/- 0,1 mm
Nominal TCP speed	1 m/s
Collaboration operations	Free drive contact sensing speed settings limiting zones
Max. consumption in standard use	< 1500 W
Average consumption in standard use	< 900 W

Environment

Degree of protection	IP54
Noise	< 65 dB(A)
Tools	
Digital input	2
Digital output	2
Analog in	2
Output power supply	12/24 V 2/1 A
Tool connector type (end effector)	M8
Ambient temperature	0-50 °C
Ambient humidity	90% RH (non-condensing)

Modules

Modules	Nominal torque (Nm)	Max torque (Nm)	Lenght (mm)	Weight (kg)	Module speed (°/s)	Movement range (°)
M1	271	621	120	7	101,25	∞
M2	149	402	100	4,5	105	∞
M3	81	225	80	3,5	72	∞
BD1200	-	-	360	2,5	-	-
BD900	-	-	210	2	-	-
BC1200	-	-	380	3	-	-
BC900	-	-	230	2,5	-	-

CONTROL BOX

Degree of protection	IP54
Ambient temperature	0-50 °C
I/O ports*	<i>*There is space to add other I/O parts.</i>
Digital input	16
Digital output	16
Analog input	2
Analog output	2
Digital input - Safety	4
Digital output - Safety	4
I/O power supply	24 V 2 A
Dimensions (WxHxD)	600x280x300 mm
Weight	< 16 kg
Materials	Aluminium, steel
Communication	ETHERCAT ETHERNET + on demand
Power supply	200-240 VAC / 47-63 Hz
Ambient humidity	90% RH (non-condensing)

TEACH PENDANT

Degree of protection	IP54
Ambient humidity	90% RH
Display resolution	1280 x 800 pixels
Materials	Plastic
Weight including 5 m TP cable	< 2 kg
Cable length	5m (can be changed on demand)